

Advantage4

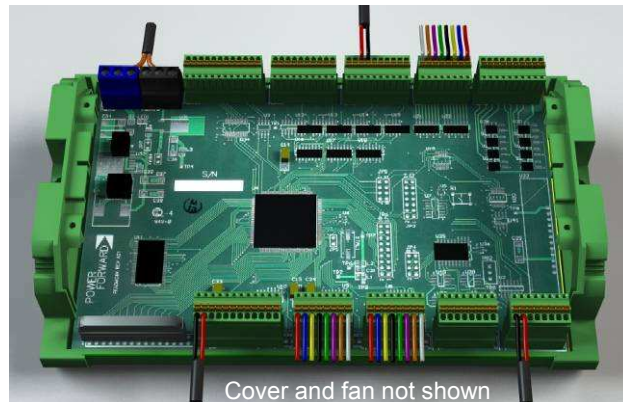
Proprietary DSP Motion Controller

Specification sheet

Simple, Powerful, Easy to Use

Developed to meet our own exceptional requirements

- ❑ **4 Axes of Motion**
 - Velocity, acceleration, profiling, synchronization, etc.
 - Multiple boards can be connected through CAN Bus
- ❑ **100% Accuracy**
 - No errors, not even rounding
- ❑ **Easy Interfaces**
 - For mounting and device connection
- ❑ **Compact Packaging**
 - All connectors on outside of board



Technically speaking ...

- ✓ 4 axes of closed loop servo control using advanced PID algorithms with velocity and acceleration feed forward. Sample times as low as 250 μ s per axis.
- ✓ Comprehensive motion control algorithms such as E-Gearing, E-Camming, point-to-point positioning, linear interpolation and much more.
- ✓ Small Din Rail mountable package with quick release terminals. All terminals (except power ground) are screwless and include probing port for monitoring voltage levels.
- ✓ Hi-Co and Lo-Co encoding at high speeds
- ✓ Inputs/Outputs:
 - 16 Opto-isolated inputs capable of high speed axis registration
 - 8 fully protected low-side smart power Mosfet outputs
 - 8 Opto-isolated solid state relay (SSR) outputs
 - 2 high speed RS-232C serial connections
 - 4 \pm 10v ADC channels

Designed & Manufactured by
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